

IN THE CLAIMS

Please amend as follows:

1. (currently amended) A robot apparatus charging system, comprising:
a robot apparatus on which a charging battery is mounted, and
a charging device for charging said charging battery mounted on said robot
apparatus,
wherein said robot apparatus includes charging indicating means for performing a
predetermined movement of at least one selected body part of the robot apparatus from a first
position to a second position to indicate an amount of charging in said charging battery on
charging said charging battery in said charging device.

2. (previously amended) The robot apparatus charging system according to claim 1,
characterized in that said at least one selected body part of said robot apparatus has a movable
portion and said predetermined movement is a movement to move said movable portion.

Claim 3 canceled.

4. (original) The robot apparatus charging system according to claim 1, characterized in
that said predetermined movement is a movement to notify of completion of charging of said
charging battery.

5. (original) The robot apparatus charging system according to claim 4, characterized in
that said predetermined movement is a continuous movement.

6. (original) The robot apparatus charging system according to claim 4, characterized in
that said robot apparatus has a head, and said predetermined movement is a movement to raise
said head.

7. (original) The robot apparatus charging system according to claim 4, characterized in

that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

8. (original) The robot apparatus charging system according to claim 4, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

9. (original) The robot apparatus charging system according to claim 4, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

10. (currently amended) The robot apparatus charging system according to claim 4, characterized in that said robot apparatus has a speaker, and said indicating means ~~predetermined movement~~ is a movement to make a sound through said speaker.

11. (currently amended) The robot apparatus charging system according to claim 4, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said indicating means ~~predetermined movement~~ is a movement to output said voice generated by said voice generating means through said speaker.

12. (currently Amended) A robot apparatus comprising charging indicating means for performing, on charging a charging battery mounted thereon, a predetermined movement of at least one selected body part of the robot apparatus from a first position to a second position to indicate an amount of charging of said charging battery during charging of said charging battery in a charging device.

13. (previously amended) The robot apparatus according to claim 12, characterized in that said selected body part of said robot apparatus has a movable portion and said predetermined movement is a movement to move said movable portion.

Claim 14 canceled.

15. (original) The robot apparatus according to claim 12, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery.

16. (original) The robot apparatus according to claim 15, characterized in that said predetermined movement is a continuous movement.

17. (original) The robot apparatus according to claim 15, characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

18. (original) The robot apparatus according to claim 15, characterized in that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

19. (original) The robot apparatus according to claim 15, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

20. (original) The robot apparatus according to claim 15, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

21. (original) The robot apparatus according to claim 15, characterized in that said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

22. (original) The robot apparatus according to claim 15, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.

23. (currently amended) A charging device for charging a charging battery mounted on a robot apparatus, characterized by causing charging indicating means of said robot apparatus, on charging said charging battery, to perform a predetermined movement of a at least one selected body part of the robot apparatus from a first position to a second position to indicate an amount of charging of said charging battery while the said robot apparatus is in the charging device.

24. (original) The charging device according to claim 23, characterized in that said robot apparatus is caused to perform said predetermined movement at completion of charging of said charging battery.

25. (original) The charging device according to claim 23, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery.

26. (currently amended) A robot apparatus charging method for charging a charging battery mounted on a robot apparatus, characterized by causing charging indicating means of said robot apparatus, on charging said charging battery in a charging device, to perform a predetermined movement of at least one selected body part of said robot apparatus from a first position to a second position to indicate an amount of charging of said charging battery while said robot apparatus is in a charging device.

27. (original) The robot apparatus charging method according to claim 26, characterized in that said robot apparatus is caused to perform a predetermined movement at completion of charging of said charging battery.

28. (original) The robot apparatus charging method according to claim 26, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery.

Claims 29 through 35 canceled.

36. (previously presented) A robot apparatus, comprising:
movement generating means for generating a movement;
detection means for detecting that a predetermined area is rocked; and
control means for controlling said movement generating means, characterized in that
when it is recognized that said predetermined area is rocked on the basis of a detection result of
said detection means in a state in which generation of said movement is stopped, said control
means controls said movement generating means to start generation of said movement wherein
said predetermined area is a body portion of the robot apparatus.

37. (currently amended) A recording medium on which is recorded a program for
charging a charging battery mounted on a robot apparatus by causing said robot apparatus, on
charging said charging battery to perform a predetermined movement in accordance with an
amount of charging of said charging battery, wherein said predetermined movement is of a at
least one selected body part of the robot apparatus from a first position to a second position while
the robot apparatus is in a charging device.

38. (previously presented) A robot apparatus charging system, comprising:
a robot apparatus on which a charging battery is mounted, and
a charging device for charging said charging battery mounted on said robot
apparatus,
characterized in that said robot apparatus performs a predetermined movement in
accordance with an amount of charging in said charging battery on charging said charging
battery using said charging device; and
wherein said predetermined movement is a movement to change a pose of said robot

apparatus form a first pose during charging to a second pose to notify of completion of charging by moving said movable portion at completion of charging of said charging battery.

39. (previously presented) A robot apparatus characterized by performing, on charging a charging battery mounted thereon, a predetermined movement in accordance with an amount of charging of said charging battery, wherein said predetermined movement is a movement to change a pose of said robot apparatus from a first pose during charging to a second pose to notify of completion of charging by moving said movable portion at completion of charging of said charging battery.

40. (currently amended) A charging device for charging a charging battery mounted on a robot apparatus, characterized by causing said robot apparatus, on charging said charging battery, to perform a predetermined movement in accordance with an amount of charging of said charging battery, wherein said predetermined movement is a movement of at least one selected body part of the robot apparatus from a first position to a second position to notify of completion of charging of said charging battery while said robot apparatus is in said charging device.

41. (currently amended) A robot apparatus charging method for charging a charging battery mounted on a robot apparatus, characterized by causing said robot apparatus, on charging said charging battery in a charging device, to perform a predetermined movement of at least one selected body part of the robot apparatus from a first position to a second position in accordance with an amount of charging of said charging battery, wherein said robot apparatus caused to perform a predetermined movement at completion of charging of said charging battery in said charging device.

42. (previously presented) A robot apparatus charging system, comprising:
a robot apparatus on which a charging battery is mounted, and

a charging device for charging said charging battery mounted on said robot apparatus,

wherein said robot apparatus includes charging indicating means for performing a predetermined movement of a body part of the robot apparatus to indicate an amount of charging in said charging battery on charging said charging battery in said charging device, and wherein

said predetermined movement is a movement to notify of completion of charging of said charging battery, and said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

43. (previously presented) A robot apparatus charging system, comprising:

a robot apparatus on which a charging battery is mounted; and

a charging device for charging said charging battery mounted on said robot apparatus;

wherein said robot apparatus includes charging indicating means for performing a predetermined movement of a body part of the robot apparatus to indicate an amount of charging in said charging battery on charging said charging battery in said charging device; and wherein

said predetermined movement is a movement to notify of completion of charging of said charging battery, and said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.

44. (new) A robot apparatus charging system, comprising:

a robot apparatus on which a charging battery is mounted, and

a charging device for charging said charging battery mounted on said robot apparatus,

wherein said robot apparatus includes charging indicating means for performing a predetermined movement of at least one selected body part of the robot apparatus to indicate an amount of charging in said charging battery on charging said charging battery in said charging device,

said at least one selected body part of said robot apparatus has a movable portion and said predetermined movement is a movement to move said movable portion, and

wherein said predetermined movement is a movement to change a pose of said robot apparatus from a first pose during charging to a second pose to notify of completion of charging by moving said movable portion at completion of charging of said charging battery.

45. (new) The robot apparatus charging system according to claim 44, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery, said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

46. (new) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

47. (new) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

48. (new) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

49. (new) The robot apparatus charging system according to claim 45, characterized in

that said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

50. (new) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.

51. (new) A robot apparatus comprising charging indicating means for performing, on charging a charging battery mounted thereon, a predetermined movement of at least one selected a body part of the robot apparatus to indicate an amount of charging of said charging battery during charging of said charging battery in a charging device,

wherein said selected body part of said robot apparatus has a movable portion and said predetermined movement is a movement to move said movable portion, and

said predetermined movement is a movement to change a pose of said robot apparatus from a first pose during charging to a second pose to notify of completion of charging by moving said movable portion at completion of charging of said charging battery.

52. (new) The robot apparatus according to claim 51, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery.

53. (new) The robot apparatus according to claim 52, characterized in that said predetermined movement is a continuous movement.

54. (new) The robot apparatus according to claim 52, characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

55. (new) The robot apparatus according to claim 52, characterized in that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

56. (new) The robot apparatus according to claim 52, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

57. (new) The robot apparatus according to claim 52, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

58. (new) The robot apparatus according to claim 52, characterized in that said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

59. (new) The robot apparatus according to claim 52, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.

60. (new) A robot apparatus charging method for charging a charging battery mounted on a robot apparatus, characterized by causing charging indicating means of said robot apparatus, on charging said charging battery in a charging device, to perform a predetermined movement of a at least one selected body part of said robot apparatus to indicate an amount of charging of said charging battery while said robot apparatus is in a charging device, said robot apparatus is caused to perform a predetermined movement at completion of charging of said charging battery, and

said predetermined movement is a movement to notify of completion of charging of said charging battery.

61. (new) The robot apparatus charging method according to claim 60, characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

62. (new) The robot apparatus charging method according to claim 60, characterized in that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

63. (new) The robot apparatus charging method according to claim 60, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

64. (new) The robot apparatus charging method according to claim 60, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

65. (new) The robot apparatus charging method according to claim 60, characterized in that said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

66. (new) The robot apparatus charging method according to claim 60, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.